
Introduction to the Finite Element method

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Motivation

A PDE:

$$\mathcal{L}u = f \quad \text{in } \Omega \subset \mathbb{R}^n, \quad \mathcal{B}u = g \quad \text{on } \partial\Omega$$

A numerical approximation:

$$\underline{\underline{A}} \, \underline{U} = \underline{R} \quad \rightarrow \quad u_h$$

- **Existence** of u, u_h .
- **Uniqueness** of u, u_h .
- **Well-posedness:** Continuous dependence on the data.
- **Convergence:** A **numerical method** is a **systematic** way of constructing approximations to u , in such a way that the difference $u - u_h$ can be made arbitrarily small (in what sense?).
- **Robustness:** u_h is **not** exact, there is some **error** but... is it an error one can tolerate (qualitatively speaking)?

Motivation

Finite Element Method: When the PDE is **elliptic**, the most popular approximation method is the FEM. It is **general, geometrically flexible, easy to code, robust**, etc. etc.

Understanding PDE's/FEM requires generalizations of the basic tools of linear algebra:

- The spaces are infinite dimensional.
- The “matrices” are now “operators” between such spaces.
- The rank theorem $\dim(\text{Ker}(\underline{\underline{A}})) + \dim(\text{Im}(\underline{\underline{A}})) = n$ no longer makes sense...(existence and uniqueness).
- Linear bijections may not have continuous inverse... (well-posedness).
- Different notions of convergence (norms) make a world of difference.

and of the basic tools of differential calculus:

- Function spaces.
- Derivatives, integrals.
- Boundary values.

Overview

- **Galerkin approximations:** Differential, variational and extremal formulations of a simple 1D boundary value problem. Well-posedness of variational formulations. Functional setting. Strong and weak coercivity. Lax-Milgram lemma. Banach's open mapping theorem. Céa's best-approximation property. Convergence under weak coercivity. (2 lectures)
- **The spaces of FEM:** (3 lectures)
- **The FEM viewed as least squares:** (1 lecture)
- **Interpolation error and convergence:** (1 lecture)
- **Application to convection-diffusion-reaction problems:** (1 lecture)
- **Application to linear elasticity:** (1 lecture)
- **Mixed problems:** (2 lectures)
- **FEM for parabolic problems:** (2 lectures)

1 Galerkin approximations

1.1 Variational formulation of a simple 1D example

Let u be the solution of

$$\begin{cases} -u'' + u = f & \text{in } (0, 1) \\ u(0) = u(1) = 0 \end{cases} \quad (1.1)$$

The **differential formulation** (DF) of the problem requires $-u'' + u$ to be exactly equal to f in **all** points $x \in (0, 1)$.

Multiplying the equation by any function v and integrating by parts (recall that

$$\int_0^1 w' z \, dx = w(1)z(1) - w(0)z(0) - \int_0^1 w z' \, dx \quad (1.2)$$

holds for all w and z that are *regular enough*) one obtains that u satisfies

$$\int_0^1 (u' v' + u v) \, dx - u'(1)v(1) + u'(0)v(0) = \int_0^1 f v \, dx \quad \forall v. \quad (1.3)$$

- The requirement “for all x ” of the DF has become “for all functions v ”.
- Does equation (1.3) fully determine u ?
- What happened with the boundary conditions?

Consider the following problem in **variational formulation** (VF): “Determine $u \in W$, such that $u(0) = u(1) = 0$ and that

$$\int_0^1 (u' v' + u v) dx = \int_0^1 f v dx \quad (1.4)$$

holds for all $v \in W$ satisfying $v(0) = v(1) = 0$.”

Prop. 1.1 *The solution u of the DF (eq. 1.1) is also a solution of the VF if W consists of continuous functions of sufficient regularity. As a consequence, problem VF admits at least one solution whenever DF does.*

Proof. Following the steps that lead to the VF, it becomes clear that the only requirement for u to satisfy (1.4) is that the integration by parts formula (1.2) be valid. \square

Exo. 1.1 *Show that the solution of*

$$\begin{cases} -u'' + u = f & \text{in } (0, 1) \\ u(0) = 0, & u'(1) = g \in \mathbb{R} \end{cases} \quad (1.5)$$

is a solution to: “Find $u \in W$ such that $u(0) = 0$ and that

$$\int_0^1 (u' v' + u v) dx = \int_0^1 f v dx + g v(1) \quad (1.6)$$

holds for all $v \in W$ satisfying $v(0) = 0$.”

Consider the following problem in **extremal formulation** (EF): “Determine $u \in W$ such that it minimizes the function

$$J(w) = \int_0^1 \left(\frac{1}{2} w'(x)^2 + \frac{1}{2} w(x)^2 - f w \right) dx \quad (1.7)$$

over the functions $w \in W$ that satisfy $w(0) = w(1) = 0$.”

Prop. 1.2 *The unique solution u of (1.1) is also a solution to EF. As a consequence, EF admits at least one solution.*

Proof. We need to show that $J(w) \geq J(u)$ for all $w \in W_0$, where

$$W_0 = \{w \in W, w(0) = w(1) = 0\}$$

Writing $w = u + \alpha v$ and replacing in (1.7) one obtains

$$J(u + \alpha v) = J(u) + \alpha \left[\int_0^1 (u' v' + u v - f v) dx \right] + \alpha^2 \int_0^1 \left(\frac{1}{2} v'(x)^2 + \frac{1}{2} v(x)^2 \right) dx$$

The last term is not negative and the second one is zero. \square

Exo. 1.2 *Identify the EF of the previous exercise.*

Prop. 1.3 *Let u be the solution of*

$$\begin{cases} -u'' + u = f & \text{in } (0, 1) \\ u(0) = 1, \quad u'(1) = g \in \mathbb{R} \end{cases} \quad (1.8)$$

then u is also a solution of “Determine $u \in W$ such that $u(0) = 1$ and that

$$\int_0^1 (u' v' + u v) \, dx = \int_0^1 f v \, dx + g v(1) \quad (1.9)$$

holds for all $v \in W$ satisfying $v(0) = 0$.”

Further, defining for any $a \in \mathbb{R}$

$$W_a = \{w \in W, w(0) = a\},$$

u minimizes over W_1 the function

$$J(w) = \int_0^1 \left(\frac{1}{2} w'(x)^2 + \frac{1}{2} w(x)^2 - f w \right) \, dx - g w(1). \quad (1.10)$$

Exo. 1.3 *Prove the last proposition.*

Let us define the bilinear and linear forms corresponding to problem (1.1):

$$a(v, w) = \int_0^1 (v'w' + vw) \, dx \qquad \ell(v) = \int_0^1 f v \, dx \qquad (1.11)$$

and the function $J(v) = \frac{1}{2}a(v, v) - \ell(v)$. Remember that W is a space of functions with some (yet unspecified) regularity and let $W_0 = \{w \in W, w(0) = w(1) = 0\}$.

The three formulations that we have presented up to now are, thus:

DF: Find a function u such that

$$-u''(x) + u(x) = f(x) \qquad \forall x \in (0, 1), \qquad u(0) = u(1) = 0$$

VF: Find a function $u \in W_0$ such that

$$a(u, v) = \ell(v) \quad \forall v \in W_0$$

EF: Find a function $u \in W_0$ such that

$$J(u) \leq J(w) \qquad \forall w \in W_0$$

and we know that the exact solution of DF is also a solution of VF and of EF.

The logic of the construction is justified by the following

Theorem 1.4 *If W is taken as*

$$W = \{w : (0, 1) \rightarrow \mathbb{R}, \int_0^1 w(x)^2 dx < +\infty, \int_0^1 w'(x)^2 dx < +\infty\} \stackrel{\text{def}}{=} H^1(0, 1)$$

and if f is such that there exists $C \in \mathbb{R}$ for which

$$\int_0^1 f(x) w(x) dx \leq C \sqrt{\int_0^1 w'(x)^2 dx} \quad \forall w \in W_0 \quad (1.12)$$

then problems (VF) and (EF) have one and only one solution, and their solutions coincide.

The proof will be given later, now let us consider its consequences:

- The differential equation has at most one solution in W .
- If the solution u to (VF)-(EF) is regular enough to be considered a solution to (DF), then u is the solution to (DF).
- If the solution u to (VF)-(EF) is not regular enough to be considered a solution to (DF), then (DF) has no solution.

\Rightarrow (VF) is a generalization of (DF).

Exo. 1.4 Show that $W_0 \subset C^0(0,1)$. Further, compute $C \in \mathbb{R}$ such that

$$\max_{x \in [0,1]} |w(x)| \leq C \sqrt{\int_0^1 w'(x)^2 dx} \quad \forall w \in W_0$$

Hint: You may assume that $\int_0^1 f(x)g(x) dx \leq \sqrt{\int_0^1 f(x)^2 dx} \sqrt{\int_0^1 g(x)^2 dx}$ for any f and g (Cauchy-Schwarz).

Exo. 1.5 Consider $f(x) = |x - 1/2|^\gamma$. For which exponents γ is $\int_0^1 f(x)w(x) dx < +\infty$ for all $w \in W_0$?

Exo. 1.6 Consider as f the “Dirac delta function” at $x = 1/2$, that we will denote by $\delta_{1/2}$. It can be considered as a “generalized” function defined by

$$\int_0^1 \delta_{1/2}(x) w(x) dx = w(1/2) \quad \forall w \in C^0(0,1)$$

Prove that $\delta_{1/2}$ satisfies (1.12) and determine the analytical solution to (VF).

Exo. 1.7 Determine the DF and the EF corresponding to the following VF: “Find $u \in W = H^1(0,1)$, $u(0) = 1$, such that

$$\int_0^1 (u'w' + uw) dx = w(1/2) \quad \forall w \in W_0 \tag{1.13}$$

where $W_0 = \{w \in W, w(0) = 0\}$.”

1.2 Variational formulations in general

Let V be a Hilbert space with norm $\|\cdot\|_V$. Let $a(\cdot, \cdot)$ and $\ell(\cdot)$ be bilinear and linear forms on V satisfying (continuity), for all $v, w \in V$,

$$a(v, w) \leq N_a \|v\|_V \|w\|_V, \quad \ell(v) \leq N_\ell \|v\|_V \quad (1.14)$$

This last inequality means that $\ell \in V'$, the (topological) dual of V . The minimum N_ℓ that satisfies this inequality is called the norm of ℓ in V' , i.e.

$$\|\ell\|_{V'} \stackrel{\text{def}}{=} \sup_{0 \neq v \in V} \frac{\ell(v)}{\|v\|_V} \quad (1.15)$$

The abstract VF we consider here is:

$$\text{“Find } u \in V \text{ such that } \quad a(u, v) = \ell(v) \quad \forall v \in V\text{”} \quad (1.16)$$

Exo. 1.8 Assume that V is finite dimensional, of dimension n , and let $\{\phi^1, \phi^2, \dots, \phi^n\}$ be a basis. Show that (1.16) is then equivalent to the linear system

$$\underline{\underline{A}} \underline{U} = \underline{L} \quad (1.17)$$

where

$$A_{ij} \stackrel{\text{def}}{=} a(\phi^j, \phi^i), \quad L_i \stackrel{\text{def}}{=} \ell(\phi^i) \quad (1.18)$$

and \underline{U} is the coefficient column vector of the expansion of u , i.e.,

$$u = \sum_{i=1}^n U_i \phi^i \quad (1.19)$$

Def. 1.5 The bilinear form $a(\cdot, \cdot)$ is said to be **strongly coercive** if there exists $\alpha > 0$ such that

$$a(v, v) \geq \alpha \|v\|_V^2 \quad \forall v \in V \quad (1.20)$$

Def. 1.6 The bilinear form $a(\cdot, \cdot)$ is said to be **weakly coercive** (or to satisfy an **inf-sup** condition) if there exists $\beta > 0$ such that

$$\sup_{0 \neq w \in V} \frac{a(v, w)}{\|w\|_V} \geq \beta \|v\|_V \quad \forall v \in V \quad (1.21)$$

and

$$\sup_{0 \neq v \in V} \frac{a(v, w)}{\|v\|_V} \geq \beta \|w\|_V \quad \forall w \in V \quad (1.22)$$

Exo. 1.9 Prove that strong coercivity implies weak coercivity.

Exo. 1.10 Prove that, if V is finite dimensional, then **(i)** $a(\cdot, \cdot)$ is strongly coercive iff $\underline{\underline{A}}$ is positive definite ($\underline{\underline{X}}^T \underline{\underline{A}} \underline{\underline{X}} > 0 \ \forall \underline{\underline{X}} \in \mathbb{R}^n$), and **(ii)** $a(\cdot, \cdot)$ is weakly coercive iff $\underline{\underline{A}}$ is invertible.

Exo. 1.11 Prove that, if $a(\cdot, \cdot)$ is weakly coercive, then the solution u of (1.16) depends continuously on the forcing $\ell(\cdot)$. Specifically, prove that

$$\|u\|_V \leq \frac{1}{\beta} \|\ell\|_{V'} \quad (1.23)$$

Theorem 1.7 Assuming V to be a Hilbert space, problem (1.16) is well posed for any $\ell \in V'$ if and only if (i) $a(\cdot, \cdot)$ is continuous, and (ii) $a(\cdot, \cdot)$ is weakly coercive.

A simpler version of this result is known as **Lax-Milgram lemma**:

Theorem 1.8 Assuming V to be a Hilbert space, if $a(\cdot, \cdot)$ is continuous and strongly coercive then problem (1.16) is well posed for any $\ell \in V'$.

Proof. This proof uses the so-called “Galerkin method”, which will be useful to introduce... the Galerkin method!

Let $\{\phi^i\}$ be a basis of V . Denoting $V_N = \text{span}(\phi^1, \dots, \phi^N)$ we can define $u_N \in V_N$ as the unique solution of $a(u_N, v) = \ell(v)$ for all $v \in V_N$. This generates a sequence $\{u_N\}_{N=1,2,\dots}$ in V . Further, this sequence is bounded, because

$$\|u_N\|_V^2 \leq \frac{1}{\alpha} a(u_N, u_N) = \frac{1}{\alpha} \ell(u_N) \leq \frac{\|\ell\|_{V'}}{\alpha} \|u_N\|_V \Rightarrow \|u_N\|_V \leq \frac{\|\ell\|_{V'}}{\alpha}, \quad \forall N$$

Recalling the weak compactness of bounded sets in Hilbert spaces, there exists $u \in V$ such that a subsequence of $\{u_N\}$ (still denoted by $\{u_N\}$ for simplicity) converges to u weakly. It remains to prove that $a(u, v) = \ell(v)$ for all $v \in V$. To see this, notice that

$$a(u, \phi^i) = a(\lim_N u_N, \phi^i) = \lim_N a(u_N, \phi^i) = \ell(\phi^i)$$

where the last equality holds because $a(u_N, \phi^i) = \ell(\phi^i)$ whenever $N \geq i$. Uniqueness is left as an exercise. \square

Exo. 1.12 Prove uniqueness in the previous theorem (bounded sequences may have several accumulation points).

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